



Description

The BMAC module is a digital indexer and microstep amplifier with integrated DSP controller. It can drive any bipolar stepper motor (4, 6 or 8 wires). Thanks to its smart processing unit, BMAC is suitable for both simple mono-axis applications and complex multi-axis systems.

Its 45V/2.5A_{RMS} amplifier stage makes it ideal to drive NEMA17 and NEMA23 stepper motors. Sinusoidal current generation provides good resonance immunity.

The motor can be driven in open-loop mode or in brushless mode with an external encoder. Autocom® provides motor stall protection, extended speed range and torque control without external PID controller.

BMAC implements an internal sequencer, 8 optoisolated digital I/Os and 1 analog input. The module can work in standalone mode with up to 500 commands stored in non-volatile memory.

Simple communication protocol is based on ASCII USB or RS232/485 standard. CANopen (DSP402 Motion Control profile) protocol can be implemented for multi-axis applications.

Installation and maintenance is fast and easy with plug-in connectors (module) or DIN41612 (rack) connector.



Technical Specification

BMAC	
Supply voltage	12 Vdc to 45 Vdc
Nominal current	2.5A _{RMS}
Max speed	4000RPM
Resolution	50µstep/step 10 000 positions per rev. for a 200steps per rev. motor
Digital IOs	8 IO optoisolated
Analog input	1 differential (0-10V)
Encoder input	biphase incremental encoder. differential RS422 (A, /A, B, /B, Z, /Z, 0V) on-board 5V 100mA supply.
Communication	RS485 optoisolated, 9600 to 115 200 bauds with USB or CANopen DSP402
Sequencer	500 commands memory
Protections	Overvoltage, overcurrent, short-circuit (mot. phase or supply), temperature. 5AT fuse.
Fixation	Screw slots or DIN rail mounting kit
Dimensions	rack 100x110x20mm
Certifications	RoHs, CE marking, UL PCBs.



Features

- > 2.5A stepper motor driver. Open loop or closed loop control.
- > "S curve" velocity profile for smooth motion without resonance.
- > Optimized current management to minimize thermal losses.
- > Smart move functions.
- > Interpolation mode for multiaxes (2D and 3D) applications.
- > UBS/485 or CANopen protocol.
- > Hardware and Software end-stops. User configurable.
- > Integrated sequencer. PLC-like functions.
- > DSP controller.
- > Brake driver (option).
- > 2 analog outputs (option)
- > Ballast for energy dissipation (option)

References

- BMAC** (BMAC USB RS485 module)
- BMAC-C** (BMAC CAN version module)
- BMAC-D** (BMAC USB RS485 rack)
- BMAC-CD** (BMAC CAN rack)
- DRVMI** (communication dll library)
- WINSIM2** (PC software with GUI)
- SPxxx-48** (xxx watts AC/DC power suply)
- MIB9010** (Ballast)

■ Pinout

Plug-in connector or DIN41612							
2A	+Vpower	2C	Motor A +	18A	I/O2	18C	+5V COD
4A	0Vpower	4C	Motor A -	20A	I/O3	20C	COD A
6A		6C	Motor B +	22A	I/O4	22C	COD /A
8A	0V 485 CAN	8C	Motor B -	24A	I/O5	24C	COD B
10A	Z CANH	10C		26A	I/O6	26C	COD /B
12A	/Z CANL	12C	+IANA	28A	I/O7	28C	COD I
14A	+V_IO	14C	-IANA	30A	I/O8	30C	COD /I
16A	I/O1	16C	0Vana	32A	0V_IO	32C	0V COD

DSub9 Male : RS485 or CAN bus							
1	Reserved	4	Reserved	7	Z CANH		
2	/Z CANL	5		8	Reserved		
3	0V485 CAN	6	Reserved	9	Reserved		

■ Multi-axis rack units



Midi Ingénierie implements standard 4, 8 and 12 axis rack units.
Supported fieldbus protocols:

Modbus-IDA
the architecture for distributed automation

EtherNet/IP™

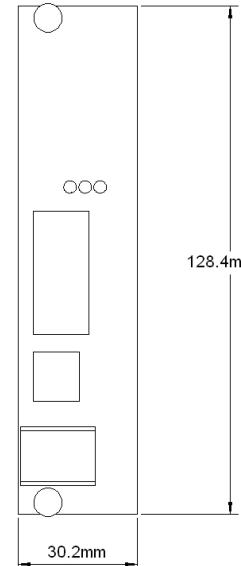
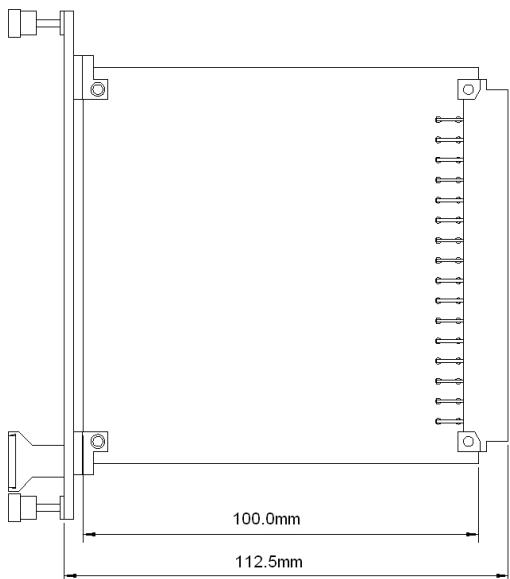
PROFIBUS®

CANopen

EtherCAT®

DeviceNet™

■ Dimension



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midi ingénierie

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